

第六届物联网、自动化和人工智能国际学术会议

会议议程 Conference Agenda

时间 / Time	主要内容 / Activity	
		5大学(东校区)第一教学楼208教室
		mpus, Guangdong Polytechnic Normal University, China t, Tianhe District, Guangzhou, Guangdong Province, China
	· •	56 / July 26, 2024
14:00-18:00	会议签到 / Sign-in	
	<u> </u>	7日 / July 27, 2024
08:00-09:00	会议签到 / Sign-in	,,,
	主持人 : 岑健教授,广东	F技术师范大学自动化学院院长 nation, Guangdong Polytechnic Normal University, China
09:00-09:05	开幕式 / Opening Ceremony	
	领导致辞 / Make a Speech	
09:05-09:15	广东省计算机学会代表致辞 校方代表致辞:戴青云校长,广东技术师范大学	Speech by Representative of Guangdong Computer Society Speech by university representative: Dai Qingyun, President of Guangdong Polytechnic Normal University, China
09:15-09:25	合影环节 / Group Photo	
	主题报告 / K	eynote Speeches
09:25-10:00	Giancarlo Fortino, IEEE Fellow, University of Calabria, Italy Title: Edge Intelligence for the Next-generation IoT Systems	
10:00-10:35	游科友,清华大学 Keyou You, Tsinghua University, China Title: Minimum Sample Data for Direct Data-driven Analysis and Adaptive LQR Design of Unknown Linear Systems	
10:35-10:50	茶歇&海报展示 / Tea Break & Poster Presentations	
10:50-11:25	邓飞其,中国自动化学会会士,华南理工大学 Feiqi Deng, CAA Fellow, South China University of Technology, China Title: Sufficient and Necessary Condition for the Asymptotic Stability of Stochastic Systems With Discrete Time Feedbacks and Applications	
11:25-12:00	唐宇,广东技术师范大学 Yu Tang, Guangdong Polytechnic Normal University, China Title: Advance and prospects of agricultural information acquisition technique for digital orchard integrating UAV and ground equipment	
12:05-14:00	午餐 / Lunch	
	Mode	erator: TBD
14:00-14:35	马大中,东北大学 Dazhong Ma, Northeastern University, China Title: Research on the Safe Operation of Energy Interconnection Systems Based on Artificial Intelligence	
14:35-15:10	舒磊,南京农业大学 Lei Shu, Nanjing Agricultural University, China Title: Farmland Guardian - Applications and Research of Artificial Intelligence in Agriculture	
15:10-15:25	茶歇&海报展示 / Tea Break & Poster Presentations	
15:25-17:05	口头报告 / Oral Presentations	
17:05-17:10	会议闭幕 / Closing Ceremony	
	2024年7月28	3日 / July 28, 2024
09:00-18:00	离会返程 / Departure	



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口头报告 Oral Presentations

时间 / Time	报告信息 / Information	
15:25-15:35	黄剑锋,惠州学院 报告题目:锂离子电池自动贴带设备:动态性能仿真及优化设计 Jianfeng Huang, Huizhou University, China Title: Automatic Tape-Application Equipment for Lithium-Ion Batteries: Dynamic Performance Simulation and Optimization Design	
15:35-15:45	李帅辰,中国科学院国家授时中心 报告题目:基于改进智能优化算法的室内超宽带定位 Shuaichen Li, National Time Service Center, Chinese Academy of Sciences, China Title: Indoor UWB Localization Based on Improved Intelligent Optimization Algorithms	
15:45-15:55	乔诗淇, 西安工程大学 报告题目:深度学习驱动的多模态情感分析 Shiqi Qiao, Xi'an Polytechnic University, China Title: Deep Learning-Driven Multimodal Sentiment Analysis	
15:55-16:05	容世强,广东药科大学 报告题目:糖尿病智能问答系统中命名实体识别算法的研究 Shiqiang Rong, Guangdong Pharmaceutical University, China Title: Research on Named Entity Recognition Algorithm for Diabetes Intelligent Question and Answer System	
16:05-16:15	贺承浩,西藏大学 报告题目:基于图文多模态融合对齐的藏汉机器翻译方法研究 Chenghao He, Tibet University, China Title: Research on Tibetan-Chinese Machine Translation Method Based on Graphic Multimodal Fusion Alignment	
16:15-16:25	胡正雨,云南电网有限责任公司电力科学研究院 报告题目:结合视觉转换器和注意机制的输电线路鸟巢检测 Zhengyu Hu, Yunnan Power Grid Co.Ltd. Electric Power Research Institute, China Title: Combining Vision Transformer and Attention Mechanism for Bird Nest Detection on Power Transmission Line	
16:25-16:35	王科敏,广东白云学院 报告题目:时延估计模型与机器人网络控制研究 Kemin Wang, Guangdong Baiyun University, China Title: Time Delay Estimation model and Robot Network Control Research	
16:35-16:45	孙海天,西北农林科技大学 报告题目:夜间实时分级尾灯跟踪 Haitian Sun, Northwest A&F University, China Title: Real-time Hierarchical Rear-lamp Tracking at Nighttime	
16:45-16:55	昌嘉怡,华南师范大学 报告题目:基于自适应直觉模糊局部信息C均值聚类的视网膜血管分割 Jiayi Chang, South China Normal University, China Title: Retinal vascular segmentation based on adaptive intuitionistic fuzzy local information C-means clustering	
16:55-17:05	王志乾,成都飞机工业集团有限责任公司 报告题目: 飞机进气道特种作业机器人技术研究 Zhiqian Wang, Chengdu Aircraft Industry Group Co., Ltd., China Title: Research On Special Operation Robot Technology For Aircraft Inlet	