

评优公示

为了弘扬大会精神，促进学术成果交流。第四届机器人、人工智能与智能控制国际会议（RAIIC 2025）组委会根据《RAIIC 2025 评优奖励通知》的相关评审要求，本着公平、公正、公开的原则，经会议主办方及评审嘉宾评选，组委会审核后，确定了第四届机器人、人工智能与智能控制国际会议（RAIIC 2025）“优秀论文、优秀青年学者报告、优秀海报”评优名单，为进一步增强评优工作的透明度，现将评优名单结果进行公示。

| 奖项 | 姓名 | 单位 | 题目 |
|----------|-----|----------|--|
| 优秀论文 | 裴国蓉 | 北京航空航天大学 | Passive Fault-Tolerant Control of Flying-Wing UAV with Actuator Faults Based on Conventional Fixed-Wing Autopilots |
| | 徐学宁 | 新疆大学 | Intermittent-based fixed-time scaled consensus for nonlinear multi-agent systems |
| 优秀青年学者报告 | 马浩天 | 内蒙古工业大学 | Automated Profiling Cutting of Salix Psammophila: A Vision Servo System Integrating YOLOv5n and U-Net for Stubble-Cutting Machine |
| | 彭伟姝 | 南昌大学 | An extended q-rung orthopair fuzzy multi-attribute decision making method based on novel information measures and its real world application |
| | 张宇俊 | 南昌大学煥奎书院 | Predicting the risk of overactive bladder in American population exposed to heavy metals: evidence from explainable machine learning methods |
| | 汤春彬 | 贵州大学 | Steel defect detection based on YOLOv12 |
| 优秀海报 | 杜申奥 | 国防科技大学 | Autonomous positioning system for UAV scene matching under GNSS-denied environments |
| | 杨彭娟 | 杭州电子科技大学 | Adaptive leader-following bipartite consensus of nonlinear multi-agent systems with matching uncertainties |
| | 袁顺 | 重庆三峡学院 | Research on detection method of papaya maturity based on YOLOv8n-ARC |
| | 曹浩天 | 中国科学技术大学 | Multi-Bionic Fish Collaborative Navigation Simulation Based on Reinforcement Learning |

*最终解释权归会议组委会

